



The data should be read in conjunction with the Magnetron Preamble.

### **ABRIDGED DATA**

ixed frequency pulse magnetron.
perating frequency 9490 $\pm$ 30 MHz
1 Inimum peak output power
Magnet integral
utput no. 16 waveguide
(22.86 x 10.16 mm internal)
oupler UG-40B/U
(NATO S.N. 5985-99-083-0051)
ooling natural or forced-air

# **GENERAL**

# **Electrical**

Cathode						inc	directly I	neated
Heater voltage (see note 1	1)						. 6.3	V
Heater current at 6.3 V							. 0.55	Α
Heater starting current, pe	eak	va	lue	,				
not to be exceeded .							. 3.0	A max
Cathode pre-heating time	(m	inir	nuı	m)				
(see note 2)							60	S

### Mechanical

Overall dimens	ions											see	0	ıtline
Net weight .											1.5	kg	ар	prox
Mounting posi	tion													any
A minimum cle	earan	ice	of	50	mr	n	mus	t be	ma	aint	aine	ed b	etv	veen

. . . . . . . . . . natural or forced-air

# **MAXIMUM AND MINIMUM RATINGS** (Absolute values)

These ratings cannot necessarily be used simultaneously, and no individual rating should be exceeded.

	Min	Max
Heater voltage (see note 1)	. 5.7	6.9 V
Heater starting current (peak)	_	3.0 A
Anode voltage (peak)	. 7.5	8.2 kV
Anode current (peak)	. 6.0	10 A
Input power (peak)		75 kW
Input power (mean) (see note 3) .		85 W
Duty cycle		0.0015
Pulse duration		2.0 μs
Rate of rise of voltage pulse		
(see notes 4 and 5)		200 kV/μs
Anode temperature (see note 6) .		120 °C
VSWR at the output coupler		1.5:1

# **TYPICAL OPERATION Operating Conditions**

					Oscillation			
					1	2		
Heater voltage					. 6.3	6.3	8 V	
Anode current (peak)					. 8.0	8.0	) A	
Pulse duration					. 1.0	0.1	μs	
Pulse repetition rate					500	1000	pps	
Rate of rise of voltage	рι	ulse			120	120	kV/μs	
Typical Performa	an	се						
Anode voltage (peak)					. 8.0	8.0	kV	
Output power (peak)					27	27	kW	
Output power (mean)					13.5	2.7	' W	

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the magnet and any magnetic materials.

### **TEST CONDITIONS AND LIMITS**

The magnetron is tested to comply with the following electrical specification.

#### **Test Conditions**

	Oscillation	Oscillation	
	1	2	
Heater voltage (for test)	6.3	6.3	V
Anode current (mean)	4.0	0.8	mA
Duty cycle	0.0005	0.0001	
Pulse duration (see note 7)	0.5	0.05	μs
VSWR at the output coupler	1.15:1	1.15:1	max
Rate of rise of voltage pulse (see note 4):			
using hard tube pulser	. 200	200	kV/μs min
alternatively using line type pulser	. 120	120	kV/μs min

### Limits

	Min	Max	Min	Max	
Anode voltage (peak)	. 7.5	8.2	7.5	8.2	kV
Output power (mean)	. 12.5	-	2.5	-	W
Frequency (see note 8)	9460	9520	-	-	MHz
RF bandwidth at $^{1}/_{4}$ power		5.0	-	50	MHz
Frequency pulling (VSWR not less than 1.5:1)		23	-	-	MHz
Stability (see note 9)		0.1	-	0.1	%
Heater current					. see note 10
Temperature coefficient of frequency					. see note 11

### LIFE TEST

The quality of all production is monitored by the random selection of tubes which are then life-tested under Test Conditions Oscillation 1. If the tube is to be operated under conditions other than those specified herein, e2v technologies should be consulted to verify that the life of the magnetron will not be impaired.

# End of Life Criteria (under Test Conditions Oscillation 1)

Anode voltage (peak) 7.5 to 8.5	kV
Output power (peak)	kW min
RF bandwidth at $^{1}/_{4}$ power 5.0	MHz max
Frequency 9460 to 9520	MHz
Stability (see note 9) 1.0	% max

### **NOTES**

1. With no anode input power.

For average values of pulse input power greater than 40 W the heater voltage must be reduced within 3 seconds after the application of HT according to the following schedule:

$$V_h = 0.08 (110 - Pi) \text{ volts}$$

where Pi = average input power in watts.

The magnetron heater must be protected against arcing by the use of a minimum capacitance of 4000 pF shunted across the heater directly at the input terminals; in some cases a capacitance as high as 2  $\mu\text{F}$  may be necessary depending on the equipment design. For further details see the Magnetron Preamble.

2. For ambient temperatures above 0 °C. For ambient temperatures between 0 and  $-55\,$  °C the cathode preheating time is 90 seconds.

The various parameters are related by the following formula:

 $Pi = i_{apk} x v_{apk} x Du$ 

where Pi = mean input power in watts

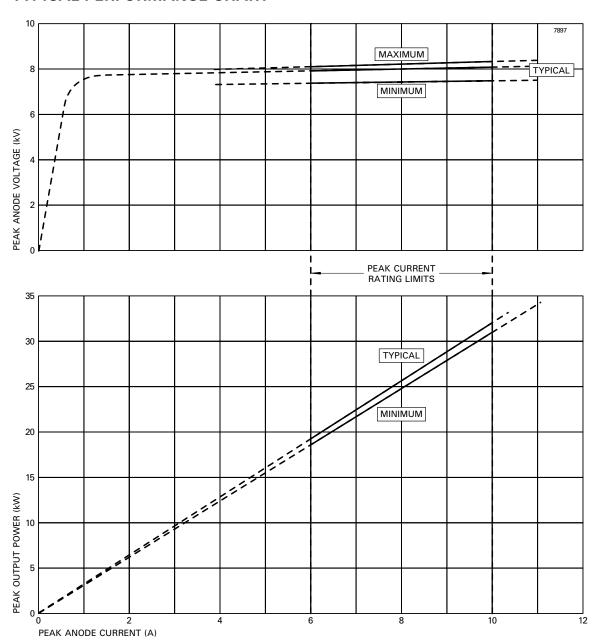
i<sub>apk</sub> = peak anode current in amperes

v<sub>apk</sub> = peak anode voltage in volts

and Du = duty cycle.

- Defined as the steepest tangent to the leading edge of the voltage pulse above 80% amplitude. Any capacitance in the viewing system must not exceed 6.0 pF.
- 5. The maximum rate of rise of voltage for stable operation depends upon detailed characteristics of the applied pulse and the pulser design. The specified maximum rating applies to typical hard tube pulsers. For minimum starting jitter and optimum operation, the recommended rate of rise of voltage for most line type pulsers is from 70 to 120 kV/μs.
- 6. The anode temperature measured at the point indicated on the outline drawing must be kept below the limit specified by means of a suitable flow of air over the anode body and waveguide attachment brackets which serve as cooling fins.
- 7. Tolerance  $\pm$  40%.
- 8. Other frequency ranges can be supplied on request.
- 9. With the magnetron operating into a VSWR of 1.15:1. Pulses are defined as missing when the RF energy level is less than 70% of the normal energy level in a 0.5% frequency range. Missing pulses are expressed as a percentage of the number of input pulses applied during the period of observation after a period of 10 minutes operation.
- Measured with heater voltage of 6.3 V and no anode input power, the heater current limits are 0.43 A minimum, 0.60 A maximum.
- 11. Design test only. The maximum frequency change with anode temperature change (after warming) is  $-0.25\ \text{MHz/}$   $^{\circ}\text{C}.$

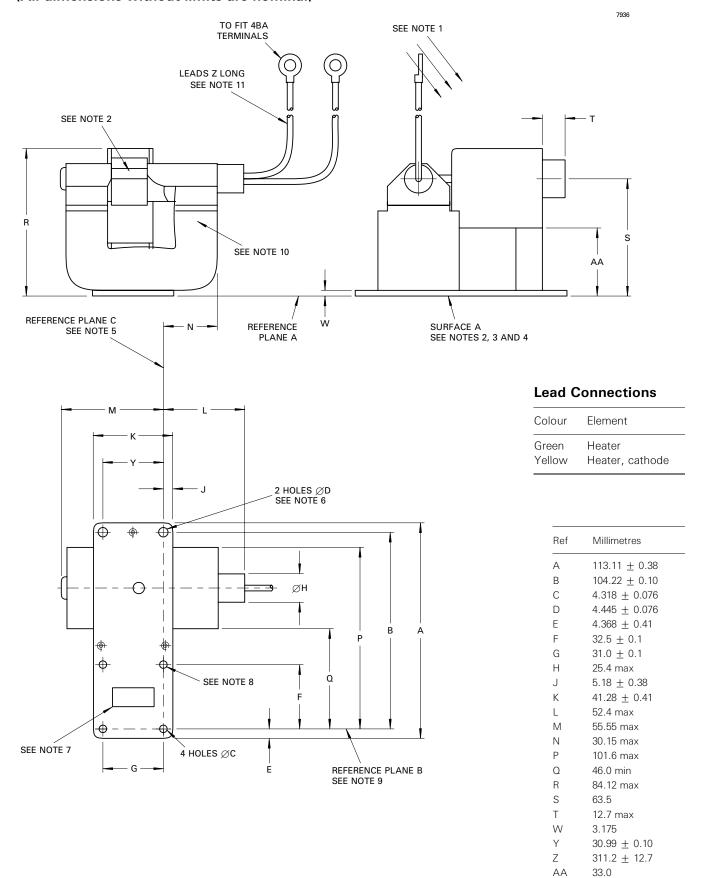
# **TYPICAL PERFORMANCE CHART**



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# **OUTLINE**

# (All dimensions without limits are nominal)



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### **Outline Notes**

- 1. Recommended direction of air flow if required.
- 2. Anode temperature measured at this point.
- 3. With surface A resting on a flat surface plate, a feeler gauge 0.51 mm thick and 3.18 mm wide will not enter more than 3.18 mm at any point.
- 4. Surface A and interior surfaces of the waveguide will be plated with 1.55 mg/cm² of gold or 4.65 mg/cm² of silver, but will not be plated if the parts are made of monel or equivalent corrosion resistant materials. All other metal surfaces will be painted with heat resistant paint or otherwise treated to prevent corrosion.
- Reference plane C intersects plane B at the centre of the mounting plate hole as shown and is mutually perpendicular to reference planes A and B.
- These holes will lie within 0.127 mm of the indicated centres. A cylinder of 8.38 mm diameter and centred on these holes will clear the side of the magnet.
- The position of the waveguide hole is not specified on this drawing since tubes are tested and used with coupler UG-40B/U (NATO S.N. 5985-99-083-0051).
- 8. The centre of this hole will lie within 0.102 mm of reference plane C.
- Reference plane B passes through the centres of the two holes of the mounting plate as shown and is perpendicular to reference plane A.
- 10. The north seeking pole of the magnet will be adjacent to the cathode sidearm.
- Length of flying leads measured from the centre line of the anode block.

# **HEALTH AND SAFETY HAZARDS**

e2v technologies magnetrons are safe to handle and operate, provided that the relevant precautions stated herein are observed. e2v technologies does not accept responsibility for damage or injury resulting from the use of electronic devices it produces. Equipment manufacturers and users must ensure that adequate precautions are taken. Appropriate warning labels and notices must be provided on equipments incorporating e2v technologies devices and in operating manuals.



# **High Voltage**

Equipment must be designed so that personnel cannot come into contact with high voltage circuits. All high voltage circuits and terminals must be enclosed and fail-safe interlock switches must be fitted to disconnect the primary power supply and discharge all high voltage capacitors and other stored charges before allowing access. Interlock switches must not be bypassed to allow operation with access doors open.



# **RF Radiation**

Personnel must not be exposed to excessive RF radiation. All RF connectors must be correctly fitted before operation so that no leakage of RF energy can occur and the RF output must be coupled efficiently to the load. It is particularly dangerous to look into open waveguide or coaxial feeders while the device is energised. Screening of the cathode sidearm of high power magnetrons may be necessary.



### X-Ray Radiation

High voltage magnetrons emit a significant intensity of X-rays not only from the cathode sidearm but also from the output waveguide. These rays can constitute a health hazard unless adequate shielding for X-ray radiation is provided. This is a characteristic of all magnetrons and the X-rays emitted correspond to a voltage much higher than that of the anode.

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